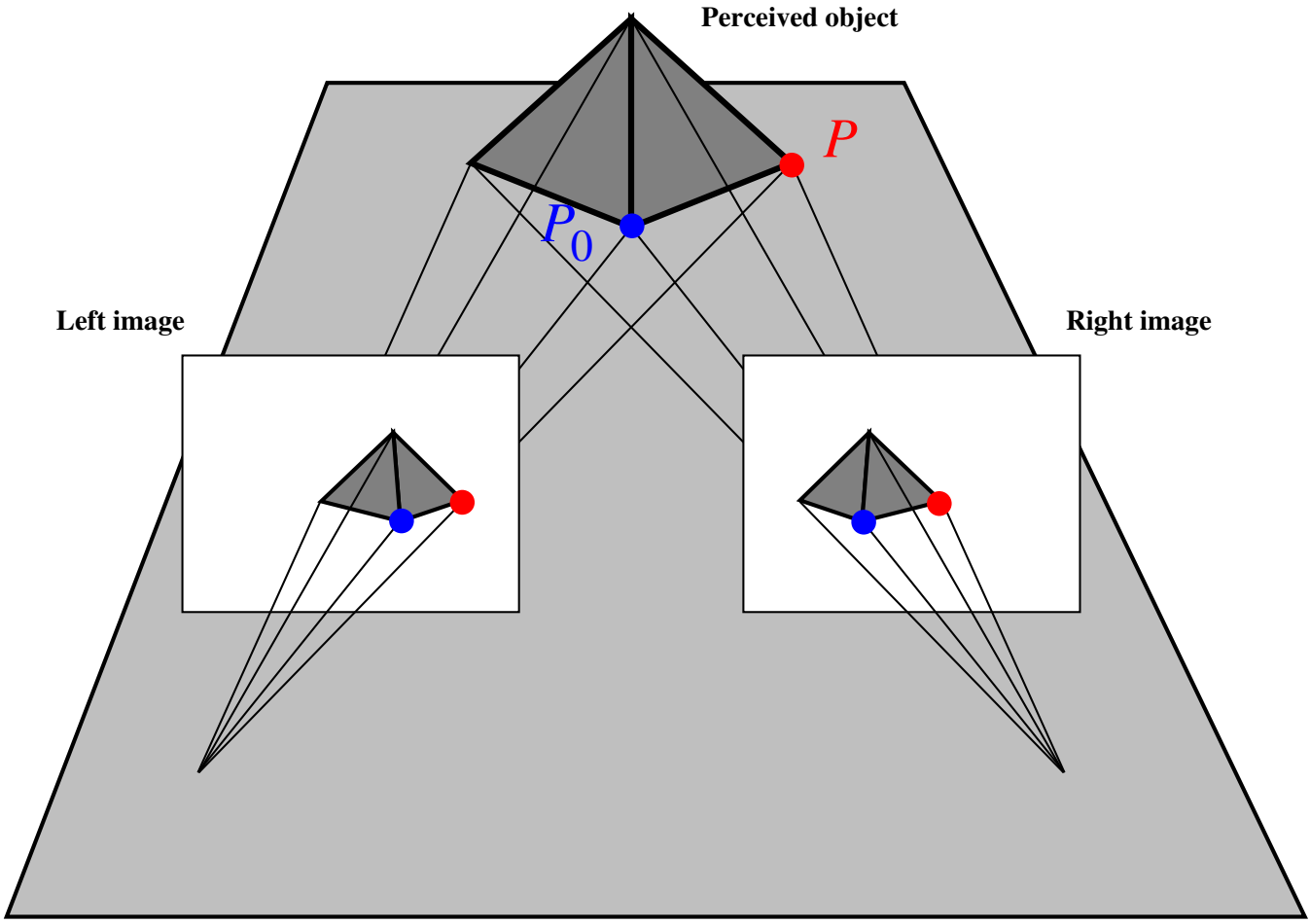
Perceived object
P
P_0
Left image
Right image