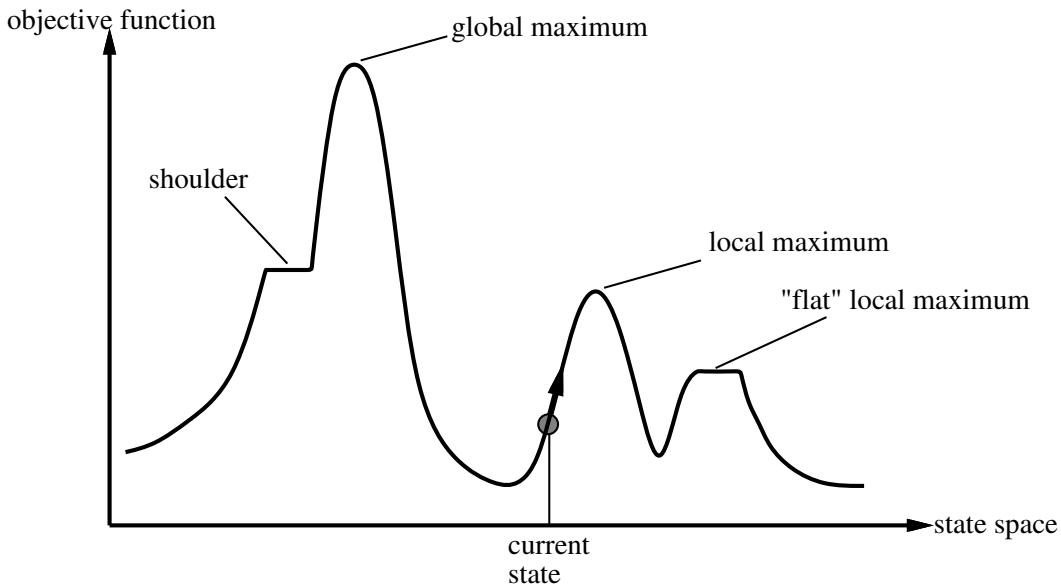
objective function
global maximum
shoulder
local maximum
"flat" local maximum
state space
current
state